Orientalmotor

Brushless Motor and Driver Package DC Power Supply Input, High Power

Series

Standard Type/Electromagnetic Brake Type

Introducing the new high power, DC input BLV Series brushless motor and driver with output options of 200 W to 400 W.

Communication control through I/O or RS-485 is available to support a wide variety of applications.



Features

DC Power Supply Input, High Power Output Options of 200 W to 400 W, Compact Motor

The BLV Series are compact, DC input brushless motors and drivers with output options of 200 W to 400 W.

An extensive variety of motors lets you select the model that best suits your specific application.

Output Power		200 W	400 W
Frame Size		□104 mm	□104 mm
Power Supply Voltage		24 VDC	48 VDC
Motor Tupo	Standard Type	•	•
Motor Type	Electromagnetic Brake Type		

Three Types Available (Shown below are standard type models):





Combination Type - Hollow Shaft Flat Gearhead

Features of the Hollow Shaft Flat Gearhead

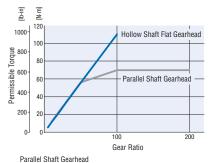
□104 mm, space-saving, hollow shaft flat gearhead has been added to the lineup.

Combination Motor Output	Gear Ratio	Rated Life
200 W, 400 W	5*, 10, 15, 20, 30, 50, 100	5000 hrs.

*Only compatible with the 400 W type.

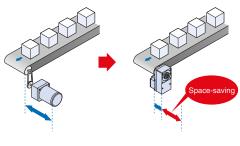
♦ Permissible Torque without Saturation

The hollow shaft flat gearhead enables permissible torque without saturation so the motor torque can be fully utilized.



♦ Space-saving

The output shaft can be coupled directly to a driven shaft without using a coupling, which allows you to reduce the size and installation space of your equipment.



[For Three-Phase Motor and Parallel Shaft Gearhead]

[For Brushless Motor and Hollow Shaft Flat Gearhead]

Comes in an Electromagnetic Brake Type

The electromagnetic brake type is suitable for position holding during standstill or gravitational operation. Note that vertical drive (gravitational operation) requires motors of a specific power supply.

Drive	Drive System		Electromagnetic Brake Type
Horizontal Drive	Switching Power Supply	•*	•*
	Battery	•	•
Vertical Drive (Gravitational	Switching Power Supply	_	_
Operation)	Battery	_	

^{*}Power supply limits depend on use. Please contact the nearest Oriental Motor sales office for details.

Extended Functions

Functions can be extended and settings shown on a digital display by using a separately sold control module (**OPX-2A**).

It can also be used in RS-485 communication mode.



Control Module
OPX-2A

Equipped with Functions to Facilitate Battery Drive

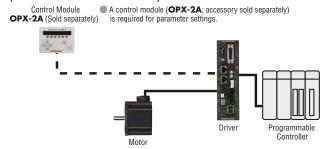
- Capable of driving even if the battery voltage is low
- A warning output notifies when the battery voltage is low

Item	Standard Model	Extended Function	
Specifications 100~4000 r/min (speed range 1:40)		Speed Control Range: 80~4000 r/min (speed range 1:50) Speed Regulation: ±0.2%	
Function	Speed setting (internal speed potentiometer, external analog setting) Acceleration time, deceleration time Torque limiting	Various Display Functions: Operating speed (setting of gear ratio and speed increasing ratio), conveyor transportation speed, load factor, alarm code, warning code, I/O monitor Operating data digital settings (speed, torque limiting, acceleration time, deceleration time can be set up to 8 points) I/O signal allocation, test operation Data cony	

Selectable Dual Control Method

Control from a programmable controller can be I/O control or RS-485 communication control.

Operation can be executed easily with I/O control.



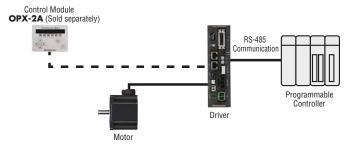
Control Method for Data Settings and Operation Commands

Operating Data and Parameter Settings		Operation Commands (FWD, REV, etc.)
Operating Data	Driver potentiometer, control module (OPX-2A)	1/0
Parameters	Control module (OPX-2A)	

♦ RS-485 Communication System

RS-485 communication lets you set operating data and parameters and enter operation commands. A single programmable controller connects up to 31 drivers and provides multi-axis synchronous starting.

The protocol of the RS-485 communication system supports Modbus RTU, allowing it to easily connect with programmable controllers, touch panels and other devices.



Control Method for Data Settings and Operation Commands

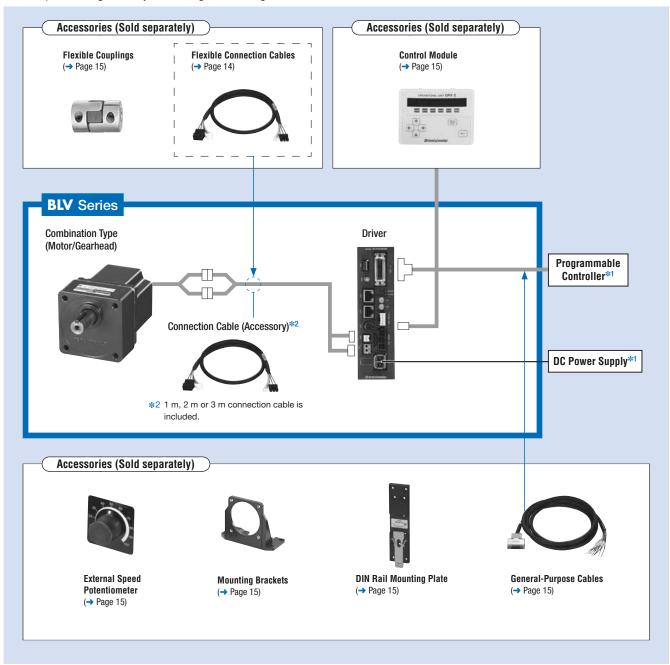
Operation Data and	Operation Commands
Parameter Setting	(FWD, REV, etc.)
RS-485 communication, control module (OPX-2A)	RS-485 communication, I/O

- FWD input, REV input and other operation commands can also be controlled from I/O.
- The test operation function is available with the control module (OPX-2A).
- The internal potentiometers for Speed, Acceleration/Deceleration and Torque Limiting are still active even when using either the control module (OPX-2A) or RS-485 comunication.

System Configuration

An example of a single-axis system configuration using I/O control is shown below.

*1 Parts sold separately.



Examples of System Configuration

BLV Series			Sold Sep	parately	
Combination Type - Parallel Shaft	+	External Speed Potentiometer	DIN Rail Mounting Plate	Mounting Brackets	Flexible Coupling
BLV620K30S-3		PAVR-20KZ	PADP03	SOL6M8	MCL652022

The system configuration shown above is an example of the standard type. Other combinations are available.

Product Number Code

1	Series	BLV : BLV Series
2	Motor Frame Size	6: 104 mm [Gearhead Frame Size: 110 mm]
3	Output Power (W)	20 : 200 W 40 : 400 W
4	Power Supply Voltage	K: 24 VDC N: 48 VDC
(5)	M: Electromagnetic Brake	e Type Blank: Standard Type
6	Gear Ratio/Shaft Type	Number: Parallel shaft gearhead type Gear ratio 5~200 Hollow shaft flat gearhead Gear ratio 5~100 A: Round Shaft Type
7	Gearhead Type (Combination type only)	S: Parallel Shaft Gearhead F: Hollow Shaft Flat Gearhead
8	Cable Length (Included)	1:1 m 2:2 m 3:3 m

Product Line

Combination Type

The combination type comes with the motor and its dedicated gearhead pre-assembled simplifying installation in equipment. Motors and gearheads are also available separately to facilitate changes or repairs.

Standard Type

Output Power	Power Supply Voltage	Model	Gear Ratio
200 W	24 VDC	BLV620K□S-◇	5, 10, 15, 20, 30, 50, 100, 200
400 W	48 VDC	BLV640N□S-♦	5, 10, 15, 20, 30, 50, 100, 200

The following items are included in each product. -

Motor, Driver, Gearhead, Connection Cable*, Power Connector, Mounting Screws, Parallel Key, Operating Manual *A cable of 1 m, 2 m or 3 m long is included.

○Round Shaft Type

Output Power	Power Supply Voltage	Model
200 W	24 VDC	BLV620KA-♦
400 W	48 VDC	BLV640NA-♦

The following items are included in each product.

Motor, Driver, Connection Cable*, Power Connector, Operating Manual *A cable of 1 m, 2 m or 3 m long is included.

Electromagnetic Brake Type

Output Power	Power Supply Voltage	Model	Gear Ratio
200 W	24 VDC	BLV620KM□S-◇	5, 10, 15, 20, 30, 50, 100, 200
400 W	48 VDC	BLV640NM□S-◇	5, 10, 15, 20, 30, 50, 100, 200

The following items are included in each product.

Motor, Driver, Gearhead, Connection Cable*, Power Connector, Mounting Screws, Parallel Key, Operating Manual

*A cable of 1 m, 2 m or 3 m long is included.

Output Power	Power Supply Voltage	Model
200 W	24 VDC	BLV620KMA-♦
400 W	48 VDC	BLV640NMA-♦

The following items are included in each product. -

Motor, Driver, Connection Cable*, Power Connector, Operating Manual *A cable of 1 m, 2 m or 3 m long is included.

Output Power	Power Supply Voltage	Model	Gear Ratio
200 W	24 VDC	BLV620K□F-◇	10, 15, 20, 30, 50, 100
400 W	48 VDC	BLV640N□F-◇	5, 10, 15, 20, 30, 50, 100

The following items are included in each product. -

Motor, Driver, Gearhead, Connection Cable*, Power Connector, Mounting Screws, Parallel Key, Safety Cover (with screws), Operating Manual *A cable of 1 m, 2 m or 3 m long is included.

Output Power	Power Supply Voltage	Model	Gear Ratio
200 W	24 VDC	BLV620KM□F-◇	10, 15, 20, 30, 50, 100
400 W	48 VDC	BLV640NM□F-◇	5, 10, 15, 20, 30, 50, 100

The following items are included in each product.

Motor, Driver, Gearhead, Connection Cable*, Power Connector, Mounting Screws, Parallel Key, Safety Cover (with screws), Operating Manual *A cable of 1 m, 2 m or 3 m long is included.

[■] Enter the gear ratio in the box (□) within the model name. Enter the length of the connection cable (included) as 1 [1 m], 2 [2 m] or 3 [3 m] in the diamond (♦) within the model name.

Specifications

Standard Type

♦ 200 W, 400 W (RoHS)

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	Combination Type – Parallel Sha	ft Gearhead	BLV620K□S-♦	BLV640N□S-♦	
Model	Combination Type – Hollow Shaft	Flat Gearhead	BLV620K□F-♦	BLV640N□F-♦	
	Round Shaft Type		BLV620KA-◇	BLV640NA-♦	
Rated Output Power (C	Continuous)	W	200	400	
	Rated Voltage	VDC	24	48	
Power Source	Permissible Voltage Range		±1	0%	
Power Source	Rated Input Current	А	13	11	
	Maximum Input Current	А	25	18	
Rated Torque		N∙m	0.65	1.3	
Starting Torque*1		N·m	1.15	1.8	
Rated Speed		r/min	3000		
Speed Control Range		r/min	100~4000 (Analog setting) 80~4000 (Digital setting: can be set in 1 r/min increments) [*] 2		
Round Shaft Type Permissible Load Inertia J ×10		×10 ⁻⁴ kg⋅m ²	8.75	15	
Rotor Inertia J ×10 ⁻⁴ kg·m ²		×10 ⁻⁴ kg⋅m ²	0.61	0.66	
Load			$\pm 0.5\%$ ($\pm 0.2\%$)*2 max. (0 \sim Rated torque, at rated sp	beed, at rated voltage, at normal ambient temperature)	
Speed Regulation	Voltage		$\pm 0.5\%$ ($\pm 0.2\%$)*2 max. (Rated voltage $\pm 10\%$, at rated speed, with no load, at normal ambient temperature)		
	Temperature		$\pm 0.5\%$ ($\pm 0.2\%$)*2 max. [0 \sim +40°C, at rated speed, with no load, at rated voltage]		

Electromagnetic Brake Type

♦ 200 W, 400 W (RoHS)

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	Combination Type – Parallel Sha	ft Gearhead	BLV620KM□S-♦	BLV640NM□S-♦	
Model	Combination Type - Hollow Shaft	Flat Gearhead	BLV620KM□F-♦	BLV640NM□F-♦	
	Round Shaft Type		BLV620KMA-♦	BLV640NMA-♦	
Rated Output Power (Conti	nuous)	W	200	400	
	Rated Voltage	VDC	24	48	
Power Source	Permissible Voltage Range		±1	0%	
Power Source	Rated Input Current	А	13	11	
	Maximum Input Current	А	25	18	
Rated Torque	Rated Torque N·m		0.65	1.3	
Starting Torque*1	Starting Torque ^{*1} N·m		1.15	1.8	
Rated Speed		r/min	30	000	
Canad Control Dongs		r/min	100~4000 (Analog setting)		
Speed Control Range			$80\sim4000$ (Digital setting: can be set in 1 r/min increments)*2		
Round Shaft Type Permissi	ible Load Inertia J	×10 ⁻⁴ kg⋅m ²	8.75	15	
Rotor Inertia J		×10 ⁻⁴ kg⋅m ²	0.61	0.66	
Load			$\pm 0.5\%$ ($\pm 0.2\%$)*2 max. (0 \sim Rated torque, at rated sp	peed, at rated voltage, at normal ambient temperature)	
Speed Regulation	Voltage		$\pm 0.5\%$ ($\pm 0.2\%$)*2 max. (Rated voltage $\pm 10\%$, at rated speed, with no load, at normal ambient temperature)		
	Temperature		$\pm 0.5\%$ ($\pm 0.2\%$)*2 max. [0 $\sim +40^{\circ}$ C, at rated speed, v	with no load, at rated voltage]	
Electromagnetic Brake*3	Brake Type		Power off activated type, automatically controlled by the driver		
Electromagnetic Brake	Static Friction Torque	N·m	0.65	1.3	

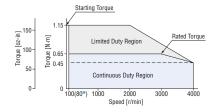
- *1 The time during which the starting torque is effective is no more than five seconds.
- *2 These specifications apply when a separately sold control module (**OPX-2A**) or communication is used.
- *3 Do not start or stop the motor by turning on/off the power supply, as it will cause the electromagnetic brake to wear abnormally.
- The values for each specification apply to the motor only.

Speed - Torque Characteristics

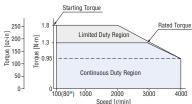
Continuous Duty Region: Continuous operation is possible in this region.

Limited Duty Region : This region is used primarily when accelerating. When a load that exceeds the rated torque is applied continuously for approximately five seconds, overload protection is activated and the motor coasts to a stop.

BLV620K\(\oplus-\circ\)/BLV620K\(\oplus-\circ\)/BLV620K\(\oplus-\circ\)/BLV620K\(\oplus-\circ\)/BLV620K\(\oplus-\circ\)



 $\begin{array}{l} {\tt BLV640N} = $$ -$ / {\tt BLV640N} = $$ -$ / {\tt BLV640NM} = $$$



*Values in parentheses indicate specifications that apply when a separately sold control module (**OPX-2A**) or communication is used. For the combination types, the values apply to the motor only.

 $[\]blacksquare$ Enter the gear ratio in the box (\square) within the model name.

Common Specifications

- Standard Model: These specifications apply when the basic motor/driver package is used.
- Extended Function: These specifications apply when a separately sold control module (OPX-2A) or communication is used.

Item		Standard Model	Extended Function*1			
Speed Setting Method		Select one of the following methods: Internal speed potentiometer (VR1) External analog setting (External speed potentiometer or external DC voltage)	Select one of the following methods: Control module (OPX-2A) Communication setting Internal speed potentiometer (VR1) External analog setting (External speed potentiometer or external DC voltage)			
Accelerati Decelerati		Acceleration and Deceleration time potentiometer (VR2): 0.2~15 seconds (3000 r/min with no load)	Select one of the following methods: Control module (with OPX-2A) or communication setting: 0.2~15 seconds (time until setting speed is achieved) Acceleration and Deceleration time potentiometer (VR2): 0.2~15 seconds (3000 r/min with no load)			
Multi-Speed Setting Method		2 Speeds: 1 speed set by the internal speed potentiometer and 1 speed set by the external analog setting	Select one of the following methods: · 8 Speeds: Control module (with OPX-2A) or communication setting · 8 Speeds: 6 speeds set by control module (with OPX-2A) and 2 speeds set by analog setting*2 *2 1 speed set by the internal speed potentiometer (VR1), and 1 speed set by the external analog setting			
Torque Limiting	Setting Method	Torque limiting potentiometer (VR3)	Select one of the following methods: Control module (with OPX-2A) Communication setting Torque limiting potentiometer (VR3) External analog setting (External torque potentiometer or external DC voltage)			
Function	Setting Range	0~200% (Assuming that the rated torque of the motor is 100%) Factory Setting: 200%	0~200% (Assuming that the rated torque of the motor is 100%)*3 Factory Setting: 200% *3 Control Module (OPX-2A) or communication setting can be set in 1% increments.			
		Photocoupler input method Input resistance 3.3 kΩ Operated by internal power supply: 15 VDC±10% Connectable external DC power supply: 24 VDC –15~+20% Current 100 mA min. Sink logic/source logic: Switchable using a switch (factory setting: sink logic)				
Input Sign	als	FWD, REV, STOP-MODE, MO, ALARM-RESET, MB-FREE	Arbitrary signal allocation to general-purpose input X0~X5 (6 points) is possible FWD [START/STOP], REV [RUN/BRAKE], STOP-MODE [FWD/REV], MB-FREE, EXT-ERROR, ALARM-RESET, HMI, M0, M1, M2 Names in [] apply in the 3-wire input mode.			
Output Sig	nale	Ex	Open-collector output ternal use condition Voltage control 200 W: 30 VDC max., 400 W: 53 VDC max. General-purpose output Y0, Y1: 100 mA max., SPEED-OUT: 10 mA max.			
output oig	gnais	SPEED-OUT, ALARM-OUT1 (Y0), WNG (Y1)	SPEED-OUT Arbitrary signal allocation to general-purpose output Y0, Y1 (2 points) is possible ALARM-OUT1, WNG, MOVE, TLC, VA, ALARM-OUT2			
Protective	Functions		ial sensor abnormality, overvoltage, undervoltage, overspeed, overcurrent, EEPROM error, main circuit overheat, , initial operation stop, communication switch setting error, main circuit output abnormality			
Warning			Main circuit overheat, undervoltage, overload, operation stop			
Maximum Cable Extension Distance			Motor/Driver Distance: 3.5 m			
Time Ratir	ng		Continuous			
			(21 1/22 1/22)			

^{*1} The contents able to be set by the driver potentiometers (VR1, VR2, VR3) or external analog settings can be changed using parameters.

General Specifications

Ite	m	Motor	Driver			
Insulation Resistance		100 M Ω or more when 500 VDC megger is applied between the windings and the case after continuous operation under normal ambient temperature and humidity. 100 M Ω or more when 500 VDC megger is applied between the power supply terminal and heat sink after continuous operation under normal ambient temperature and humidity.				
Dielectric Voltage		Sufficient to withstand 0.5 kVAC at 50 Hz applied between the windings and the case for 1 minute after continuous operation under normal ambient temperature and humidity.	Sufficient to withstand 0.5 kVAC at 50 Hz applied between the power supply terminal and heat sink for 1 minute after continuous operation under normal ambient temperature and humidity.			
Temperature Rise		60°C or less in the windings, and 50°C or less in the case*1, as measured by the thermocouple method after continuous operation under normal ambient temperature and humidity.	50°C or less in the heat sink, as measured by the thermocouple method after continuous operation under normal ambient temperature and humidity.			
	Ambient Temperature	$0{\sim}+40^{\circ}{ m C}$				
	Ambient Humidity	85% or less (n	on-condensing)			
Operating	Altitude	Up to 1000 m above sea level				
Environment	Atmosphere	No corrosive gases or dust. Cannot be used in a radioactive	e area, magnetic field, vacuum or other special environment			
	Vibration	Not subject to continuous vibration or excessive impact. In compliance with JIS C 60068-2-6, "Sine-wave vibration test method" Frequency range: 10~55 Hz Pulsating amplitude: 0.15 mm Sweep direction: 3 directions (X, Y, Z) Number of sweeps: 20 times				
	Ambient Temperature	-25~+70°C (non-freezing)				
Storage Condition*2	Ambient Humidity	85% or less (n	on-condensing)			
	Altitude	Up to 3000 m above sea level				
Thermal Class		EN standards: 120 (E)	-			
Degree of Protection		IP40	IP20			

^{*1} For round shaft types, please attach a heat radiation plate (material: aluminum) of the appropriate size listed below to maintain a maximum motor case temperature of 90°C: 200 W: 200×200 mm, 5 mm thick 400 W: 250×250 mm, 6 mm thick

Note:

Note:

The torque limiting value may cause an error up to a maximum of approximately ±20% (during rated torque and rated speed) between the setting value and generated torque due to the setting speed, power supply voltage and motor cable extension length.

^{*2} The storage condition applies to a short period such as the period during transportation.

Do not measure insulation resistance or perform the dielectric strength test while the motor and driver are connected.

Communication Specifications

Modbus Communication Specifications

Item	Specifications					
Communication Protocol	Modbus protocol (Modbus RTU mode)					
Electrical Characteristics	EIA-485-compliant					
Electrical Gridiacteristics	For use of twisted-pair wire (TIA/EIA-568B CAT5e min. recommended), set the total extension length of the communication cable at max. 50 m.					
Transmit/Receive Method	Half-duplex communication					
Baud Rate	9600 bps, 19200 bps, 38400 bps, 57600 bps, 115200 bps					
Physical Layer	Asynchronous method (Data: 8-bit, Stop-Bit: 1-bit/2-bit, Parity: Blank/Even No./Odd No.)					
Number of Connection Units	31 units max.					

Gearmotor – Torque Table of Combination Type

Combination Type – Parallel Shaft Gearhead

Unit = N·m

	Gear Ratio		5	10	15	20	30	50	100	200
Model	Motor Speed [r/min]	100 r/min	20	10	6.7	5	3.3	2	1	0.5
MOUCI		3000 r/min	600	300	200	150	100	60	30	15
		4000 r/min	800	400	267	200	133	80	40	20
DIVAN	0 □ □S-◇	100~3000 r/min	2.9	5.9	8.8	11.7	16.8	28.0	52.7	70
DLV 02	0==3-	4000 r/min	2.0	4.1	6.1	8.1	11.6	19.4	36.5	63
BLV640 □ □S-♦		100~3000 r/min	5.9	11.7	17.6	23.4	33.5	55.9	70	70
DLV04		4000 r/min	4.3	8.6	12.8	17.1	24.5	40.9	63	63

A colored background indicates gear shaft rotation in the same direction as the motor shaft, while the others rotate in the opposite direction.

Combination Type – Hollow Shaft Flat Gearhead

Unit = $N \cdot m$

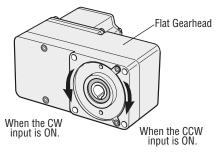
	Gear Ratio		5	10	15	20	30	50	100
Model	Motor Coood	100 r/min	20	10	6.7	5	3.3	2	1
Model	Motor Speed [r/min]	3000 r/min	600	300	200	150	100	60	30
	[1/11111]	4000 r/min	800	400	267	200	133	80	40
BLV620 □ □F-♦		100~3000 r/min	_	5.5	8.3	11.1	16.6	27.6	55.3
DLV 021	0 <u> </u> \/	4000 r/min	_	3.8	5.7	7.7	11.5	19.1	38.3
BLV640⊞□F-◇		100~3000 r/min	5.5	11.1	16.6	22.1	33.2	55.3	110
		4000 r/min	4.0	8.1	12.1	16.2	24.2	40.4	80.8

The flat gearhead rotates in the opposite direction to the motor when viewed from the front of the gearhead. It rotates in the same direction as the motor when viewed from the rear (motor mounting surface) of the gearhead.

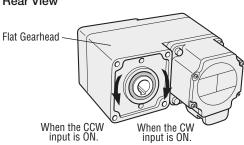
Rotation Direction of the Hollow Shaft Flat Gearhead

The hollow shaft flat gearhead of the combination type rotates in the direction as shown below, with respect to the direction input from the driver.

Front View



Rear View



[■] Enter the power supply voltage K or N (KM and NM for electromagnetic brake type) in the box (within the model name. Enter the gear ratio in the box () within the model name.

Permissible Overhung Load and Permissible Thrust Load

Combination Type – Parallel Shaft Gearhead

	Gear Ratio		Permissible 0	Permissible		
Model			10 mm from	20 mm from	Thrust Load	
			shaft end	shaft end		
			N	N	N	
	5, 10, 15, 20 30, 50	100~3000 r/min	550	800	200	
		4000 r/min	500	700	200	
BLV620 □ □S-♦		100~3000 r/min	1000	1250	300	
BLV640 □ □S-♦		4000 r/min	900	1100	300	
	100, 200	100~3000 r/min	1400	1700	400	
	100, 200	4000 r/min	1200	1400	400	

Combination Type – Hollow Shaft Flat Gearhead

			Permissible C		
Model	Gea	r Ratio	10 mm from mounting surface	20 mm from mounting surface	Permissible Thrust Load
	2		of gearhead	of gearhead	
			N	N	N
		100~3000 r/min	1230	1070	
		4000 r/min	1130	990	
BLV620 <u>□</u> □F-♦		100~3000 r/min	1680	1470	800
BLV640 □ □F-♦		4000 r/min	1550	1360	600
	30, 50, 100	100~3000 r/min	2040	1780	
	30, 30, 100	4000 r/min	1900	1660	

^{*}BLV640 □ F- ◇ only.

Round Shaft Type

	Permissible 0	verhung Load		
Model	10 mm from shaft end	20 mm from shaft end	Permissible Thrust Load	
	N	N		
BLV620□A-◇ BLV640□A-◇	197	221	The permissible thrust load should not be greater than half the motor mass.	

Permissible Load Inertia J of Combination Type

Combination Type - Parallel Shaft Gearhead

Unit = $\times 10^{-4}$ kg·m²

one in the control of						A TO Mg III			
Model	Gear Ratio	5	10	15	20	30	50	100	200
BLV620 □ □S-♦		100	460	1000	1700	3900	9300	18000	37000
BLV640□□S-♦	When instantaneous stop or instantaneous bi-directional operation is performed		150	338	600	1350	3750	3750	3750

Combination Type – Hollow Shaft Flat Gearhead

Unit = $\times 10^{-4}$ kg·m²

Model	Gear Ratio	5*	10	15	20	30	50	100
BLV620 □ □F-⇔		100	460	1000	1700	3900	9300	18000
BLV640 F-	When instantaneous stop or instantaneous bi-directional operation is performed	37.5	150	338	600	1350	3750	3750

^{*}BLV640 □ F- ◇ only.

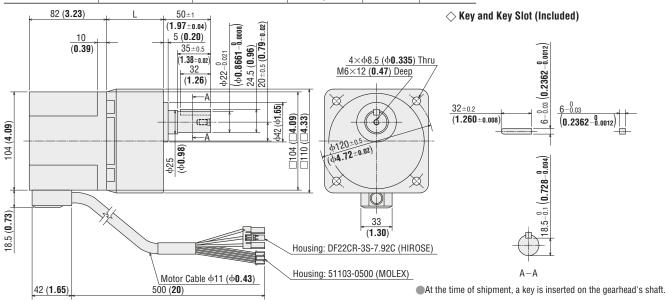
[■] Enter the power supply voltage K or N (KM and NM for electromagnetic brake type) in the box (within the model name. Enter the gear ratio in the box (
) within the model name.

Dimensions Unit = mm

Mounting screws are included with the combination type.

Standard Type 200 W, 400 W

Model	Motor Model	Gearhead Model	Gear Ratio	L	Mass kg
BD// 00//□C △	DIVALCON OFC		5~20	60	
BLV620K□S-◇ BLV640N□S-◇	BLVM620K-GFS BLVM640N-GFS	GFS6G□	30, 50	72	5.4
	BLV/VI04014-G13		100.200	86	

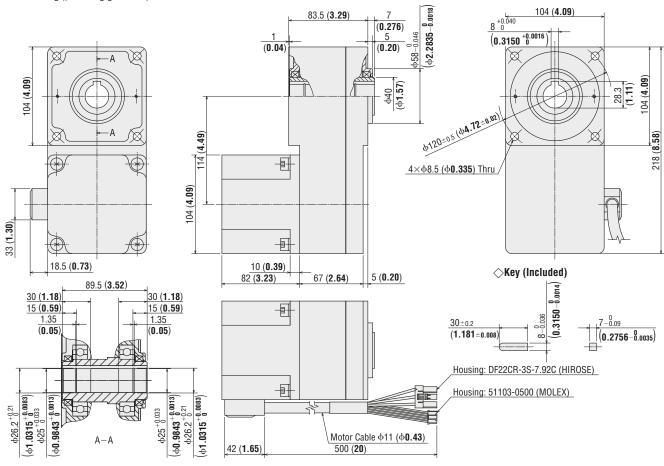


BLV620K□F-♦, BLV640N□F-♦

Motor: BLVM620K-GFS, BLVM640N-GFS

Gearhead: GFS6G□FR

Mass: 7.2 kg ((Including gearhead)

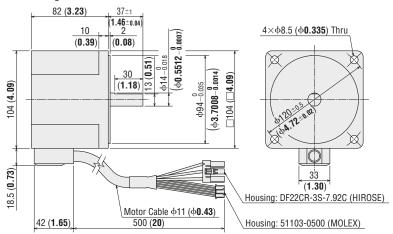


 \blacksquare Enter the gear ratio in the box (\square) within the model name.

BLV620KA-�, **BLV640NA-**�

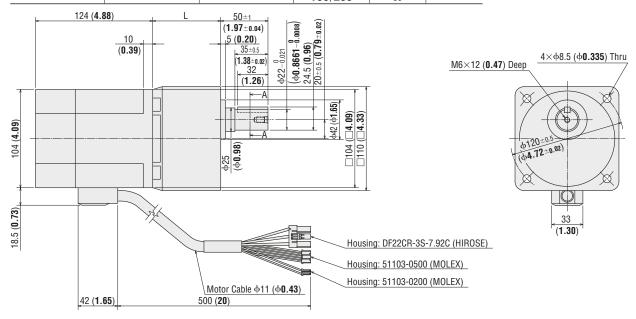
Motor: BLVM620K-A, BLVM640N-A

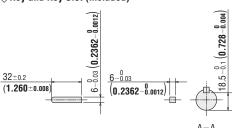
Mass: 2.4 kg



● Electromagnetic Brake Type 200 W, 400 W

	Model	Motor Model	Gearhead Model	Gear Ratio	L	Mass kg
		DIVALAGORAL CEC		5~20	60	
BLV620KM□S-♦ BLV640NM□S-♦	BLVM620KM-GFS BLVM640NM-GFS	GFS6G□	30, 50	72	6.4	
	BLV040IVM_3-	BEVIVIO401 VIVI OI 3		100 200	86	





At the time of shipment, the key is inserted on the gearhead's shaft.

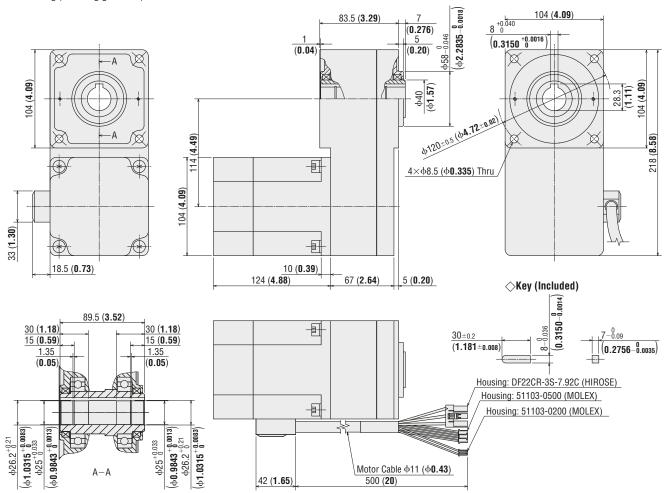
■ Enter the gear ratio in the box (□) within the model name.
Enter the length of the connection cable (included) as 1 [1 m], 2 [2 m] or 3 [3 m] in the diamond (◊) within the model name.

$BLV620KM\Box F-\diamondsuit$, $BLV640NM\Box F-\diamondsuit$

Motor: BLVM620KM-GFS, BLVM640NM-GFS

Gearhead: GFS6G□FR

Mass: 8.2 kg (Including gearhead)

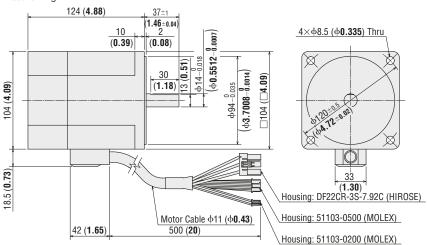


\Diamond Round Shaft Type

BLV620KMA- \diamondsuit , BLV640NMA- \diamondsuit

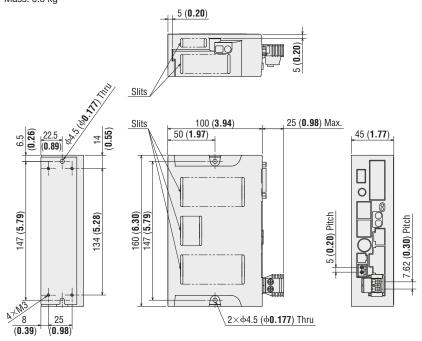
Motor: BLVM620KM-A, BLVM640NM-A

Mass: 3.4 kg



[■] Enter the gear ratio in the box (□) within the model name.

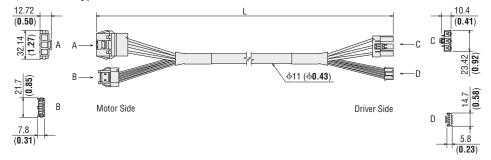
DriverBLVD20KM, BLVD40NM Mass: 0.6 kg



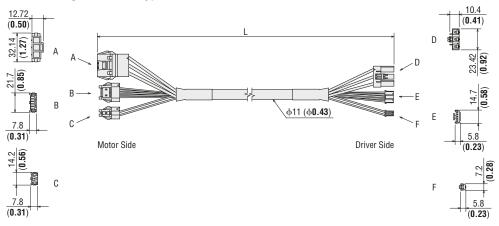
Connection Cable (Included)

Cable Type	Length L [m]
Connection Cable 1 m	1
Connection Cable 2 m	2
Connection Cable 3 m	3





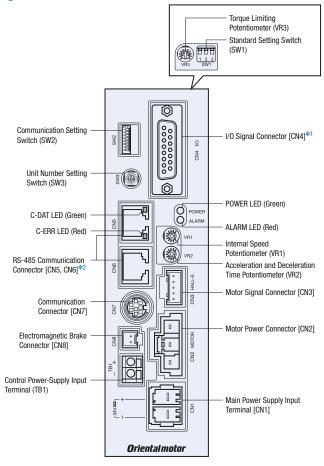
Code	Housing Product Name	Manufacturer
A	DF22R-3EP-7.92C	HIROSE
В	51198-0500	MOLEX
С	DF22CR-3S-7.92C	HIROSE
D	51103-0500	MOLEX



Code	Housing Product Name	Manufacturer
A	DF22R-3EP-7.92C	HIROSE
В	51198-0500	MOLEX
С	51198-0200	MOLEX
D	DF22CR-3S-7.92C	HIROSE
Е	51103-0500	MOLEX
F	51103-0200	MOLEX

Connection and Operation

Names and Functions of Driver Parts



- *1 The following items are needed for the connector that connects the I/O signals:
 - D-sub connector (15-pin), hood (screw: No. 4-40UNC)
 - General-purpose cable is available as an accessory. → Page 15

A connection example for sink	ogic.	Package Name In
	CN1 Driver	BLV620
DC Power Supply BLV620: 24 VDC±10% BLV640: 48 VDC±10%	⊕ ⊖	BLV640
FWD	$\begin{array}{c c} \text{CN4} & & \\ \hline & 3.3 \text{ k}\Omega & \\ \hline \end{array}$	
STOP-MODE MO	② CN3 → Motor Signal Connecto CN8 → Electromagnetic Brake	
ALARM-RESET MB-FREE IN-COM	(4) (9) (10) (6) SPEED-OUT *1 IN-COM	BLV620:30 VDC max. 10 mA max.
External DC Voltage (Within voltage selected with	(5)	BLV640: 53 VDC max. 10 mA max.
SW1 – No. 2) 3 VH VM	(13) (13) (14) (15) (14) (15) (15) (16) (17) (17) (17) (17) (17) (17) (17) (17	100 mA max. BLV640: 53 VDC max. 100 mA max.

- *1 To prevent the current value from exceeding 10 mA, connect a limiting resistor appropriate for the power supply voltage that will be used.
- *2 To prevent the current value from exceeding 100 mA, connect a limiting resistor appropriate for the power supply voltage that will be used.

Name	Description
POWER LED (Green)	Lights when main or logic power supply is on.
ALARM LED (Red)	Blinks while an alarm (protective function) occurs. The type of alarm can be confirmed by the blink count.
Internal Speed Potentiometer (VR1)	Sets the motor's speed.
Acceleration and Deceleration Time Potentiometer (VR2)	Sets the motor's starting and stopping times.
Torque Limiting Potentiometer (VR3)	Sets the motor's torque limiting value.
Main Power Supply Input Terminal [CN1]	Connects the main power supply. BLV620 : +24V, BLV640 : +48V
Motor Power Connector [CN2]	Connects the motor power connector.
Motor Signal Connector [CN3]	Connects the motor signal connector.
Electromagnetic Brake Connector [CN8]	Connects the motor electromagnetic brake connector.
I/O Signal Connector [CN4]	Used when an external control device is used or an operation command is entered.
Standard Setting Switch (SW1)	Switches the speed response, sink logic/ source logic, and the external DC voltage.
Communication Connector [CN7]	Connects to control module OPX-2A .
Control Power-Supply Input Terminal (TB1)*2	Connects the driver's power supply for signal control.
RS-485 Communication Connector [CN5, CN6]*2	Connects the RS-485 communication cable.
C-DAT LED (Green)*2	Lights when communications are normal with the master station via RS-485 communication.
C-ERR LED (Red)*2	Lights when a communication abnormality occurs with the master station via RS-485 communication.
Communication Setting Switch (SW2)*2	Sets the baud rate, communication protocol and terminating resistor of the RS-485 communication.
Unit Number Setting Switch (SW3)*2	Sets the unit number of the RS-485 communication.

*2 Used with RS-485 communications.

An RS-485 communication cable is available as an accessory.

→ Page 15

d Power Supply Capacity

Package Name	Input Power Supply Voltage	Power Supply Capacity
BLV620	24 VDC±10%	800 W min.
BLV640	48 VDC±10%	1 kW min.

Refer to the operating manual for detailed information and notes about this product. Please download the operating manual from our website or contact your nearest Oriental Motor sales office. http://www.orientalmotor.eu

List of Motor and Driver Combinations

Standard Type

Output Power	Model	Motor Model	Gearhead Model	Driver Model
200 W	BLV620K□S-♦	BLVM620K-GFS	GFS6G□	BLVD20KM
400 W	BLV640N□S-♦	BLVM640N-GFS	GF30GL	BLVD40NM

Output Power	Model	Motor Model	Gearhead Model	Driver Model
200 W	BLV620K□F-♦	BLVM620K-GFS	GFS6G□FR	BLVD20KM
400 W	BLV640N□F-♦	BLVM640N-GFS	GI30GLIK	BLVD40NM

Output Power	Model	Motor Model	Driver Model
200 W	BLV620KA-♦	BLVM620K-A	BLVD20KM
400 W	BLV640NA-♦	BLVM640N-A	BLVD40NM

Electromagnetic Brake Type

○Combination Type – Parallel Shaft Gearhead

Output Power	Model	Motor Model	Gearhead Model	Driver Model
200 W	BLV620KM□S-♦	BLVM620KM-GFS	GFS6G□	BLVD20KM
400 W	BLV640NM□S-♦	BLVM640NM-GFS	GF30G	BLVD40NM

○Combination Type – Hollow Shaft Flat Gearhead

Output Power	Model	Motor Model	Gearhead Model	Driver Model
200 W	BLV620KM□F-♦	BLVM620KM-GFS	GFS6G□FR	BLVD20KM
400 W	BLV640NM□F-⇔	BLVM640NM-GFS	GF30GLIFK	BLVD40NM

Output Power	Model	Motor Model	Driver Model
200 W	BLV620KMA-♦	BLVM620KM-A	BLVD20KM
400 W	BLV640NMA-♦	BLVM640NM-A	BLVD40NM

 $[\]blacksquare$ Enter the gear ratio in the box (\square) within the model name.

Enter the length of the connection cable (included) as 1 [1 m], 2 [2 m] or 3 [3 m] in the diamond (\Diamond) within the model name.

Accessories (Sold separately)

Flexible Connection Cables (RoHS)

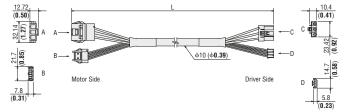
Use of flexible connection cables is recommended in applications where the cable will be bent and stretched repeatedly.

The maximum extension length is 3.5 m.

Standard Type

Model	Length L [m]
CC01BLV2R	1
CC02BLV2R	2
CC03BLV2R	3

○Dimensions Unit = mm



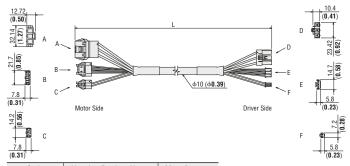
Code	Housing Product Name	Manufacturer
Α	DF22R-3EP-7.92C	HIROSE
В	51198-0500	MOLEX
С	DF22CR-3S-7.92C	HIROSE
D	51103-0500	MOLEX



Electromagnetic Brake Type

Model	Length L [m]
CC01BLV2MR	1
CC02BLV2MR	2
CC03BLV2MR	3

♦ Dimensions Unit = mm



Code	Housing Product Name	Manufacturer
Α	DF22R-3EP-7.92C	HIROSE
В	51198-0500	MOLEX
С	51198-0200	MOLEX
D	DF22CR-3S-7.92C	HIROSE
Е	51103-0500	MOLEX
F	51103-0200	MOLEX

Control Module (RoHS)

Allows for setting of various parameters and confirmation of the setting data. It is used by connecting to the driver communication connector (CN7).





■External Speed Potentiometer (RoHS)

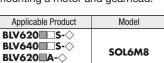
Used to set and adjust the speed of motor.





■ Motor and Gearhead Mounting Brackets (RoHS)

Dedicated mounting brackets for mounting a motor and gearhead.





Note:

BLV640**■**A-<

This mounting bracket cannot be used with the hollow shaft flat gearhead.

Flexible Couplings (RoHS)

A clamp type coupling for connecting the motor/gearhead shaft with the driven shaft. Once the motor or gearhead are chosen, the coupling can be selected.



Applicable Product	Shaft Diameter [mm]	Coupling Type
BLV620 □ □S- ◇ BLV640 □ □S- ◇	ф22	MCL65 Type
BLV620■A- ◇ BLV640■A- ◇	ф14	MCL40 Type

■DIN Rail Mounting Plate ®oHS

Use this plate when installing the driver to a DIN rail.

Model
PADP03



Driver Cable

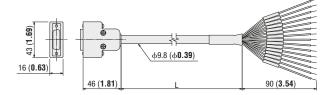
General-Purpose Cables RoHS

Dedicated 15-conductor cables for connecting the I/O signal connector and programmable controller. They are high-quality, noise-blocking, double-shielded cables.



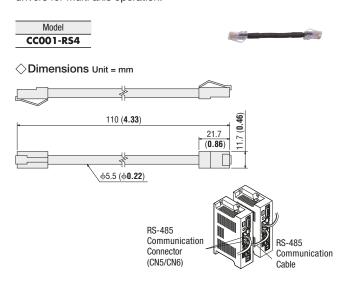
Model	Length L [m]
CC15D1	1
CC15D2	2

○ Dimensions Unit = mm



●RS-485 Communication Cable (RoHS)

This cable with connector assemblies are available to connected drivers for multi axis operation.



Enter the power supply voltage K or N (KM and NM for electromagnetic brake type) in the box (within the model name.

[■] Enter the gear ratio in the box (□) within the model name.

This product is manufactured at a plant certified with the international standards ISO 9001 (for quality assurance) and ISO 14001 (for systems of environmental management).

Oriental motor

Specifications are subject to change without notice.

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